

Optimal data-driven estimator selection with minimal penalties

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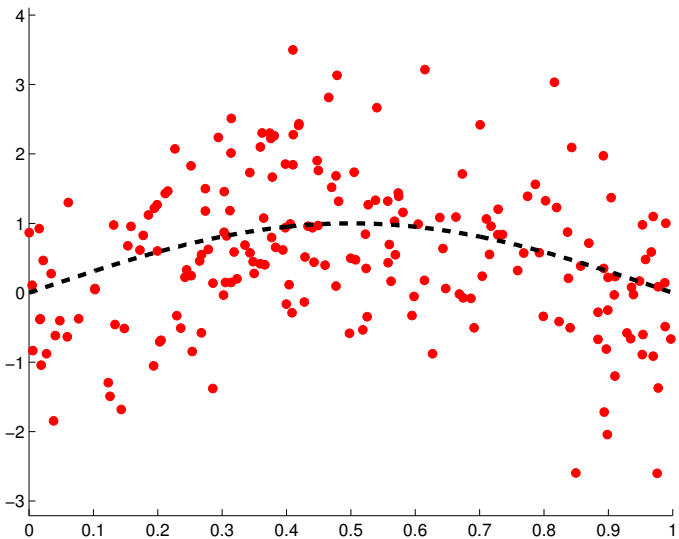
Plan

- 1 Motivation
- 2 Slope heuristics for ordinary least-squares
 - Framework
 - Optimal model selection
 - Minimal penalty and the slope heuristics
 - Theoretical results
 - Variance estimation
 - Practical considerations
- 3 Generalization: minimal penalties
 - Linear estimators
 - Slope heuristics for linear estimators
 - Minimal penalty algorithm for linear estimators
 - Minimal penalty algorithm in general
- 4 Application to multi-task learning

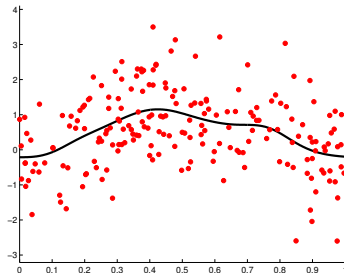
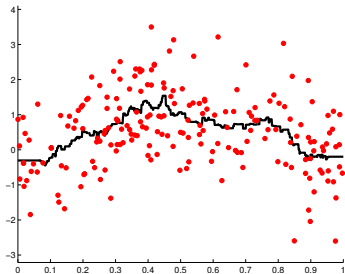
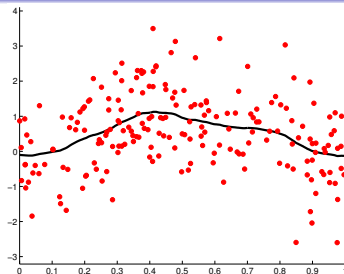
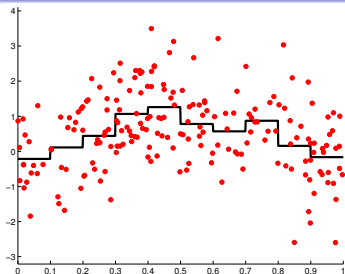
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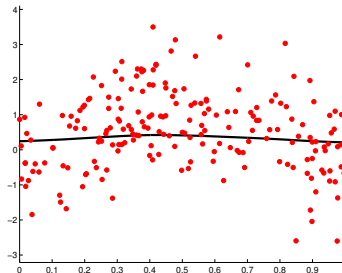
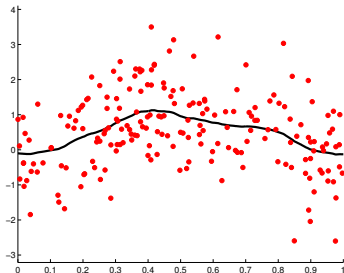
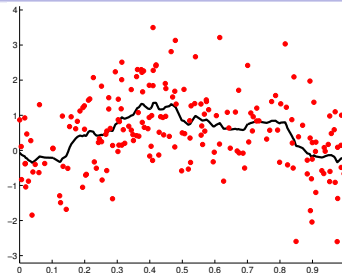
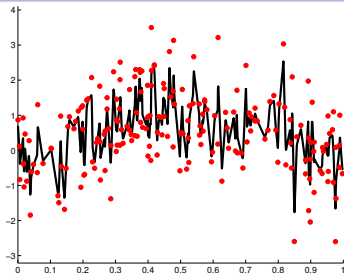
Goal: find the signal (denoising)



Estimators: regressogram, ridge, k -NN, NW



Estimator selection: kernel ridge



Estimator selection

- Estimator collection $(\hat{F}_m)_{m \in \mathcal{M}} \Rightarrow \hat{m}(Y)$?
- Goal: minimize the risk
- Examples:
 - model selection
 - parameter tuning (choosing k or the distance for k -NN, choice of a regularization parameter, choice of a kernel, etc.)
 - choice between different methods
ex.: k -NN vs. kernel ridge?
- Classical approaches and their limitations:
 - cross-validation: computational cost
 - penalization: unknown constants
 - elbow heuristics: no clear definition/justification

Penalties known up to a constant factor

$$\hat{m}(Y) \in \operatorname{argmin}_{m \in \mathcal{M}} \left\{ \text{Emp. risk}(\hat{F}_m) + \text{pen}(m) \right\}$$

- Optimal penalties depending on the noise level σ^2 (Mallows, 1973):

$$\text{pen}_{\text{CP}}(m) = \frac{2\sigma^2 D_m}{n} \quad \text{pen}_{\text{CL}}(m) = \frac{2\sigma^2 \operatorname{tr}(A_m)}{n}$$

Rk: various methods for estimating σ^2 or avoiding its estimation (FPE, Akaike, 1970; GCV, Craven & Wahba, 1978; Baraud, Giraud & Huet, 2009).

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- Resampling-based penalties
- Optimal constant unknown even in theory (change-point detection, mixture models, global/local Rademacher complexities, ...)

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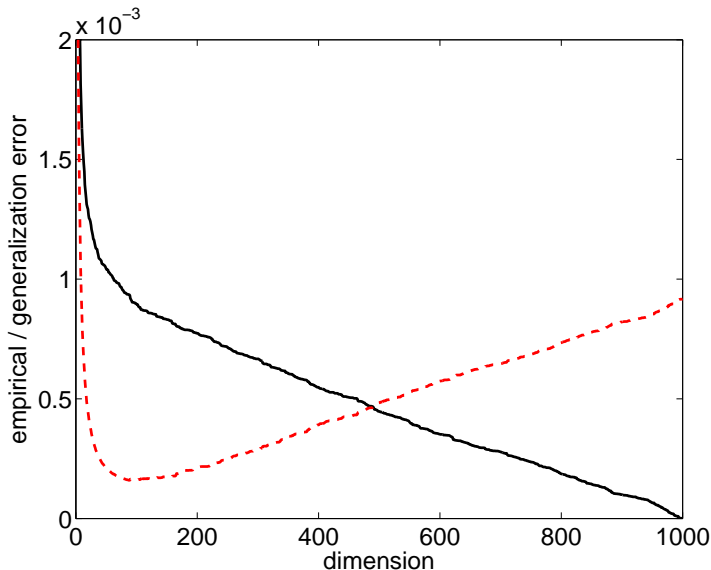
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Goals: estimation of the optimal constant (e.g., σ^2) for estimator selection, under minimal assumptions, without overfitting

“L-curve” and elbow heuristics?



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Statistical framework: regression, least-squares loss

- Observations: $Y = (Y_1, \dots, Y_n) \in \mathbb{R}^n$

$$Y_i = F_i + \varepsilon_i \quad (\text{e.g., } F_i = F(x_i))$$

with $Y_i \in \mathbb{R}$, $(\varepsilon_i)_{1 \leq i \leq n}$ i.i.d.

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- Fixed design: $x_i \in \mathcal{X}$ deterministic

Model examples

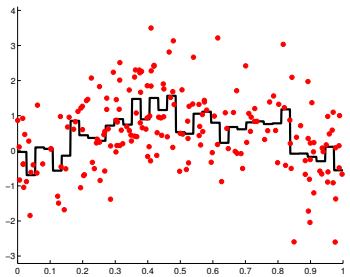
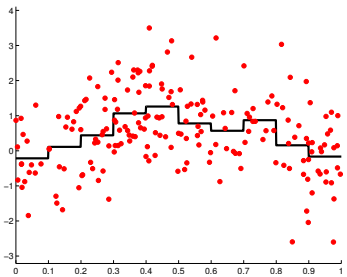
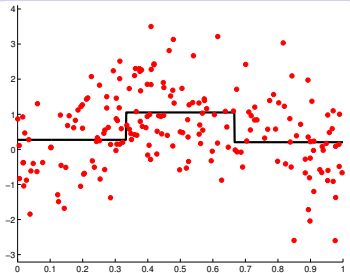
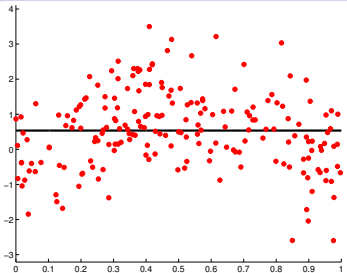
- **histograms** on some partition Λ of \mathcal{X}
⇒ the least-squares estimator (regressogram) can be written

$$\widehat{F}_m(x_i) = \sum_{\lambda \in \Lambda} \widehat{\beta}_\lambda \mathbb{1}_{x_i \in \lambda} \quad \widehat{\beta}_\lambda = \frac{1}{\text{Card}\{x_i \in \lambda\}} \sum_{x_i \in \lambda} Y_i$$

- subspace generated by a subset of an orthogonal basis of $L^2(\mu)$ (**Fourier, wavelets, ...**)
- **variable selection**: $x_i = (x_i^{(1)}, \dots, x_i^{(p)}) \in \mathbb{R}^p$ gathers p variables that can (linearly) explain Y_i

$$\forall m \subset \{1, \dots, p\} \quad , \quad S_m = \text{vect} \left\{ x^{(j)} \text{ s.t. } j \in m \right\}$$

Model selection: regular regressograms



Model selection

- Model collection $(S_m)_{m \in \mathcal{M}} \Rightarrow (\hat{F}_m)_{m \in \mathcal{M}} \Rightarrow \hat{m}(Y)?$

$$\hat{F}_m = \Pi_m Y = \Pi_{S_m} Y$$

- Goal: minimize the risk, i.e.,
Oracle inequality (in expectation or with a large probability):

$$\frac{1}{n} \left\| \hat{F}_{\hat{m}} - F \right\|^2 \leq C \inf_{m \in \mathcal{M}} \left\{ \frac{1}{n} \left\| \hat{F}_m - F \right\|^2 \right\} + R_n$$

Bias-variance trade-off

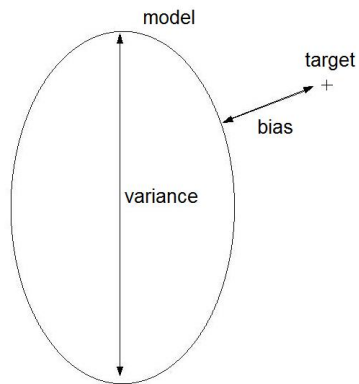
$$\mathbb{E} \left[\frac{1}{n} \left\| \widehat{F}_m - F \right\|^2 \right] = \text{Bias} + \text{Variance}$$

Bias or Approximation error

$$\frac{1}{n} \left\| F_m - F \right\|^2 = \frac{1}{n} \left\| \Pi_m F - F \right\|^2$$

Variance or Estimation error

$$\frac{\sigma^2 \dim(S_m)}{n}$$



Bias-variance trade-off

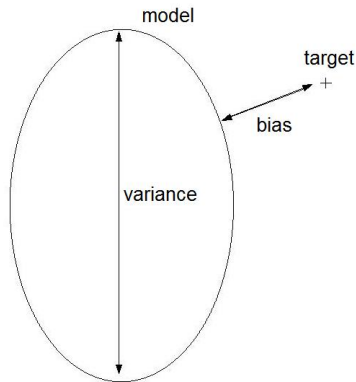
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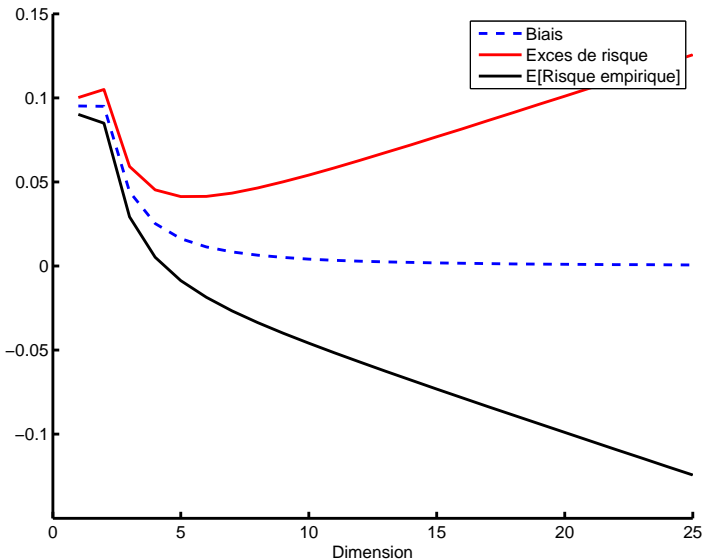
$$\frac{\sigma^2 \dim(S_m)}{n}$$



Bias-variance trade-off

⇔ avoid **overfitting** and **underfitting**

Why should the empirical risk be penalized?



Penalization

$$\hat{m} \in \underset{m \in \mathcal{M}}{\operatorname{argmin}} \left\{ \frac{1}{n} \left\| \hat{F}_m - Y \right\|^2 + \operatorname{pen}(m) \right\}$$

Penalization

$$\hat{m} \in \operatorname{argmin}_{m \in \mathcal{M}} \left\{ \frac{1}{n} \left\| \hat{F}_m - Y \right\|^2 + \operatorname{pen}(m) \right\}$$

- Ideal penalty:

$$\operatorname{pen}_{\text{id}}(m) := \frac{1}{n} \left\| \hat{F}_m - F \right\|^2 - \frac{1}{n} \left\| \hat{F}_m - Y \right\|^2 = \text{Risk} - \text{Empirical risk}$$

- **Mallows' heuristic:** $\operatorname{pen}(m) \approx \mathbb{E}[\operatorname{pen}_{\text{id}}(m)]$
 \Rightarrow oracle inequality if $\operatorname{Card}(\mathcal{M})$ not too large
 (+ concentration inequalities)

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$$\Rightarrow C_p: \quad 2\sigma^2 D_m / n \quad (\text{Mallows, 1973})$$

Oracle inequality

Theorem (Birgé & Massart 2007, reformulated)

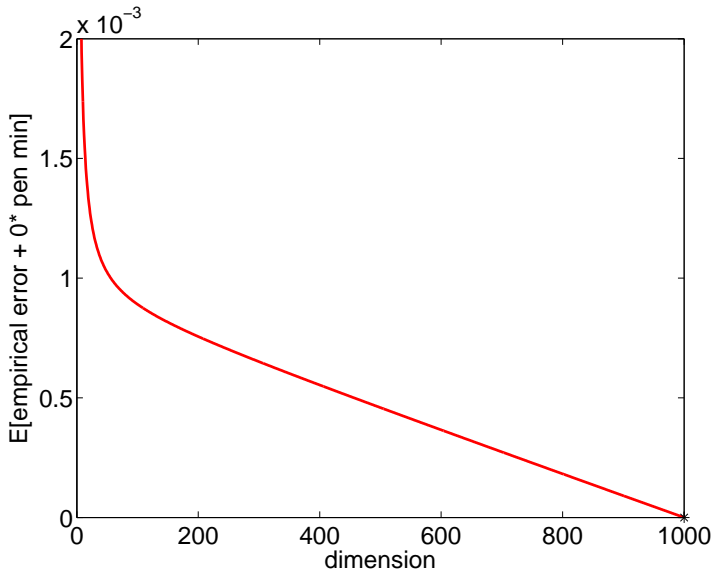
Assumptions:

- $\text{pen}(m) = \frac{2\sigma^2 D_m}{n}$
- *Gaussian noise:* $\varepsilon_i \sim \mathcal{N}(0, \sigma^2)$

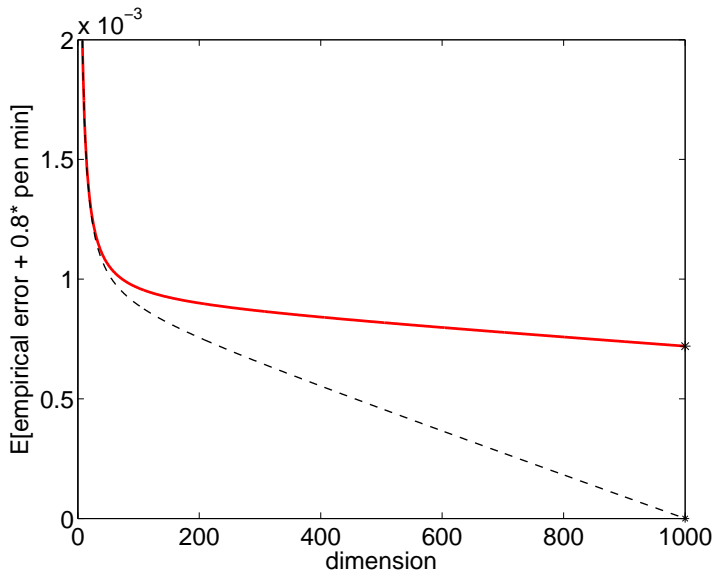
Then, for every $\gamma > 0$, with probability at least $1 - 4 \text{Card}(\mathcal{M})n^{-\gamma}$, if $n \geq n_0(\gamma)$, for every $\eta \in (0, 1)$,

$$\frac{1}{n} \left\| \hat{F}_{\hat{m}} - F \right\|^2 \leq (1 + \eta) \inf_{m \in \mathcal{M}} \left\{ \frac{1}{n} \left\| \hat{F}_m - F \right\|^2 \right\} + \frac{80\gamma \log(n)\sigma^2}{\eta n}$$

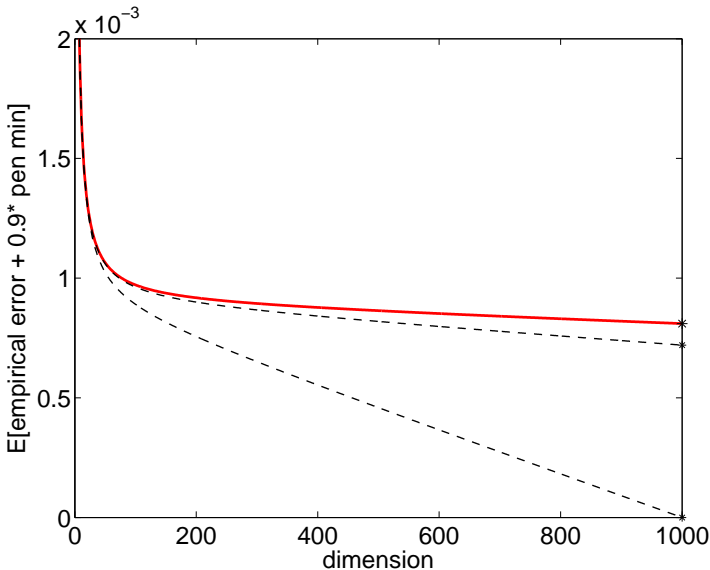
$$\mathbb{E}[\text{Empirical risk}] + 0 \times \sigma^2 D_m n^{-1} \text{ (OLS)}$$



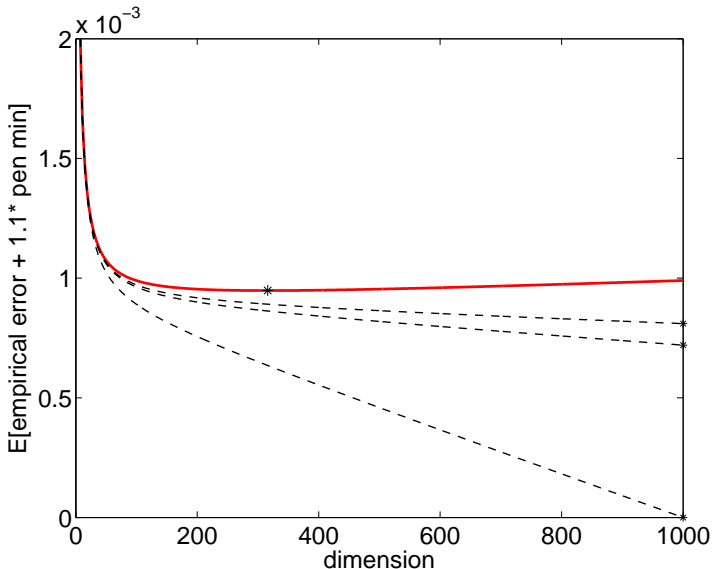
$$\mathbb{E}[\text{Empirical risk}] + 0.8 \times \sigma^2 D_m n^{-1} \text{ (OLS)}$$



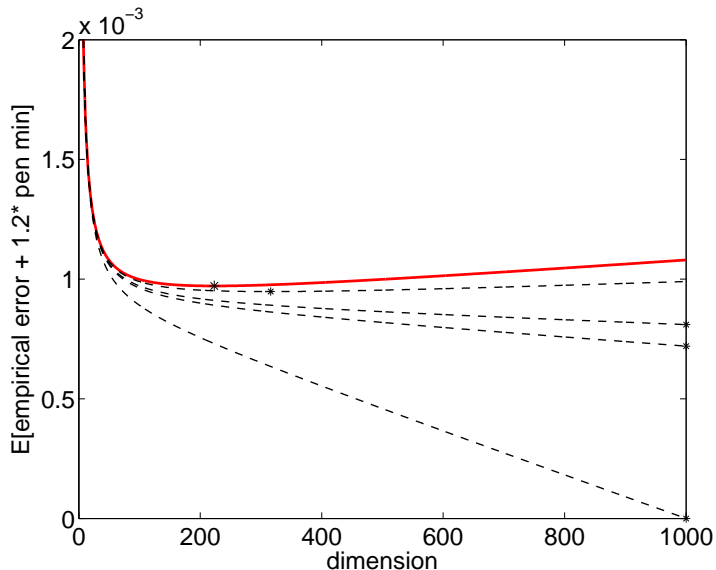
$\mathbb{E}[\text{Empirical risk}] + 0.9 \times \sigma^2 D_m n^{-1} \text{ (OLS)}$



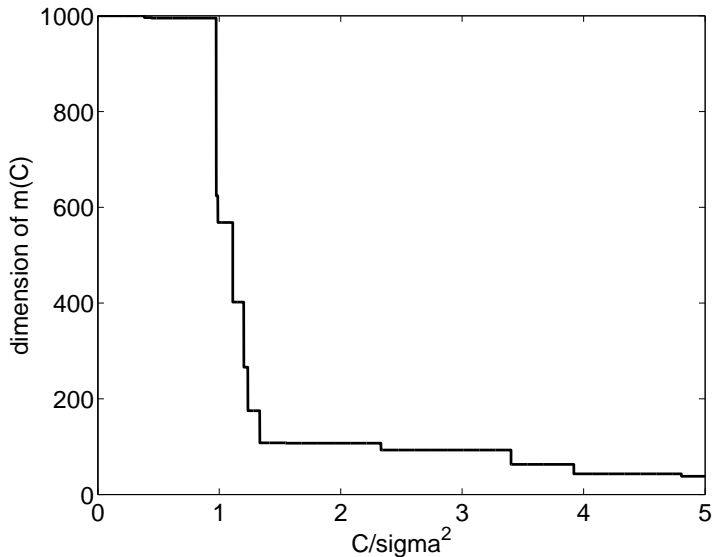
$$\mathbb{E}[\text{ Empirical risk }] + 1.1 \times \sigma^2 D_m n^{-1} \text{ (OLS)}$$



$\mathbb{E}[\text{ Empirical risk }] + 1.2 \times \sigma^2 D_m n^{-1}$ (OLS)



OLS: Dimension jump



OLS: slope heuristics algorithm (Birgé & Massart 2007)

- 1 for every $C > 0$, compute

$$\hat{m}(C) \in \underset{m \in \mathcal{M}_n}{\operatorname{argmin}} \left\{ \frac{1}{n} \left\| \hat{F}_m - Y \right\|^2 + C \frac{D_m}{n} \right\}$$

- 2 find \hat{C}_{jump} such that $D_{\hat{m}(C)}$ is “very large” when $C < \hat{C}_{\text{jump}}$ and “reasonably small” when $C > \hat{C}_{\text{jump}}$
- 3 select $\hat{m} = \hat{m} \left(2\hat{C}_{\text{jump}} \right)$

Practical use: CAPUSHE package (Baudry, Maugis & Michel, 2011)

<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

Theorem (1'): Dimension jump / Minimal penalty

Under the same assumptions, on the same event, $\forall a_n, b_n$ such that

$$\begin{aligned}
 2n\delta_n + 16.2\sqrt{\gamma \log(n)n} &< b_n < a_n < n, \\
 \forall C < (1 - \eta_n^-) \sigma^2, \quad D_{\widehat{m}(C)} &\geq a_n \\
 \forall C > (1 + \eta_n^+) \sigma^2, \quad D_{\widehat{m}(C)} &\leq b_n
 \end{aligned}$$

with

$$\begin{aligned}
 \eta_n^- &= \left(1 - \frac{a_n}{n}\right)^{-1} \sqrt{\frac{\gamma \log(n)}{n}} \\
 \eta_n^+ &= \frac{n}{b_n - n\delta_n} \left(\delta_n + 8.1\sqrt{\frac{\gamma \log(n)}{n}}\right)
 \end{aligned}$$

Increasing γ , a_n , decreasing $b_n \Rightarrow$ larger window for C
 Larger $\delta_n \Rightarrow$ larger upper bound for C & lower bound for b_n

Theorem (2): Oracle inequality

Theorem (Birgé & Massart 2007, reformulated)

Assumptions:

- $\hat{m} \in \operatorname{argmin}_{m \in \mathcal{M}} \left\{ \frac{1}{n} \|\hat{F}_m - Y\|^2 + 2\hat{C}_{\text{jump}} \frac{D_m}{n} \right\}$
- $\exists m_0 \in \mathcal{M}, S_{m_0} = \mathbb{R}^n$, i.e., $\hat{F}_{m_0} = Y$,
- $\inf_{m \in \mathcal{M}} \left\{ \mathbb{E} \left[\frac{1}{n} \|\hat{F}_m - F\|^2 \right] \right\} \leq \sigma^2 \delta_n, \delta_n \leq 1/20$,
- *Gaussian noise:* $\varepsilon_j \sim \mathcal{N}(0, \sigma^2)$.

Then, with probability at least $1 - 4 \operatorname{Card}(\mathcal{M})n^{-\gamma}$, if $n \geq n_0(\gamma)$, for every $\eta \geq 2 \max\{\eta_n^-, \eta_n^+\}$,

$$\frac{1}{n} \|\hat{F}_{\hat{m}} - F\|^2 \leq (1 + 3\eta) \inf_{m \in \mathcal{M}} \left\{ \frac{1}{n} \|\hat{F}_m - F\|^2 \right\} + \frac{880\sigma^2\gamma \log(n)}{\eta n}$$

Variance estimation

- **Slope heuristics**: with probability $1 - 4 \text{Card}(\mathcal{M})n^{-\gamma}$,

$$1 - 81\sqrt{\frac{\gamma \log(n)}{n}} \leq \frac{\hat{C}_{\text{jump}}}{\sigma^2} \leq 1 + 20\delta_n + 81\sqrt{\frac{\gamma \log(n)}{n}}$$

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$$1 - 81\sqrt{\frac{\gamma \log(n)}{n}} \leq \frac{\widehat{C}_{\text{jump}}}{\sigma^2} \leq 1 + 20\delta_n + 81\sqrt{\frac{\gamma \log(n)}{n}}$$

- Naive estimator:

$$\widehat{\sigma}_m^2 := \frac{1}{n - D_m} \left\| Y - \widehat{F}_m \right\|^2$$

$$\Rightarrow \mathbb{E} [\widehat{\sigma}_m^2] = \sigma^2 + \frac{\|(I_n - \Pi_m)F\|^2}{n - D_m}$$

Variance estimation

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- **Best variance estimator for $\mathbb{E}[(\widehat{\sigma} - \sigma)^2]$ is not necessarily the best for model selection.**

Data-driven penalties

- Naive estimator with some fixed m_0 + plug in:

$$\text{crit}(m) = \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 + \frac{2\hat{\sigma}_{m_0}^2 D_m}{n}$$

Drawbacks: choice of m_0 ? unknown bias (overpenalization)

Data-driven penalties

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Drawbacks: choice of m_0 ? unknown bias (overpenalization)

- FPE (Akaike, 1970; Baraud, Giraud & Huet, 2009)

$$\text{crit}_{\text{FPE}}(m) = \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 + \frac{2\hat{\sigma}_m^2 D_m}{n} = \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 \left(1 + \frac{2D_m}{n - D_m} \right)$$

$$\text{crit}_{\text{BGH}}(m) = \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 \left(1 + \frac{\text{pen}(m)}{n - D_m} \right)$$

Drawbacks: deal carefully with the largest models
oracle inequalities (Baraud, Giraud & Huet, 2009) hold assuming an upper bound on $\max_{m \in \mathcal{M}} D_m$ (FPE) or for a new penalty, very large for the largest models (BGH)

Generalized cross-validation (Craven & Wahba, 1978)

$$\text{crit}_{\text{GCV}}(m) = \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 \left(1 - \frac{D_m}{n} \right)^{-2}$$

If $D_m \ll n$,

$$\text{crit}_{\text{GCV}}(m) \approx \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 \frac{n + D_m}{n - D_m} = \text{crit}_{\text{FPE}}(m)$$

Drawbacks: deal carefully with the largest models

⇒ e.g., for smoothing splines, oracle inequality assumes the effective dimension is $\leq n/5$ for all m (Cao & Golubev, 2006)

Practical qualities of the algorithm

- visual checking of existence of a jump
- calibration independent from the choice of some m_0
- too strong overfitting almost impossible
- one remaining parameter: how to localize the jump

How to localize the jump in practice?

- **Dimension jump**: largest jump? jump on a geometrical window? complexity threshold?

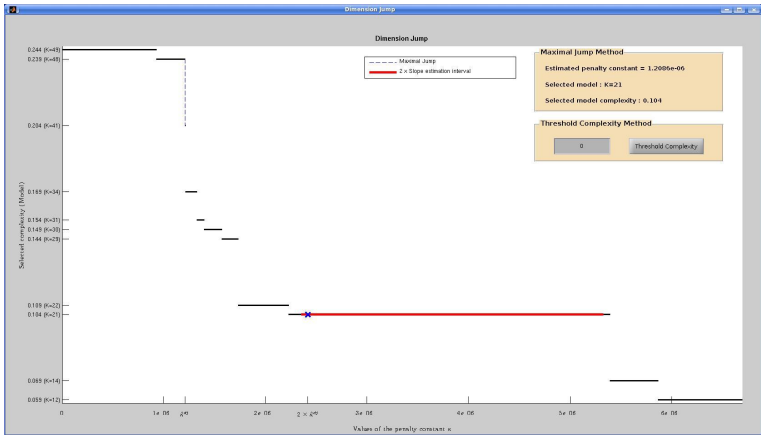
How to localize the jump in practice?

- Dimension jump: largest jump? jump on a geometrical window? complexity threshold?
- Estimation of the slope of the empirical risk as a function of the dimension:
 computed with which models? robust regression?

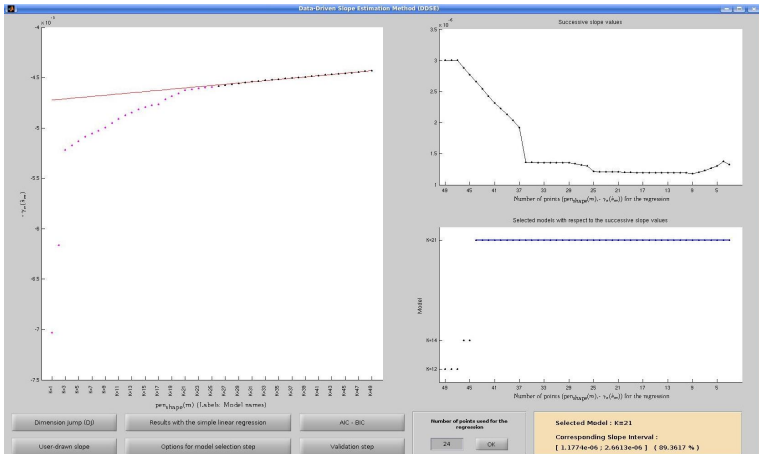
How to localize the jump in practice?

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- Estimation of the slope of the empirical risk as a function of the dimension:
computed with which models? robust regression?
- **Jump vs. slope? Take both!**
⇒ package CAPUSHE (Baudry, Maugis & Michel, 2011)
<http://www.math.univ-toulouse.fr/~maugis/CAPUSHE.html>

CAPUSHE (Baudry, Maugis & Michel, 2011): jump



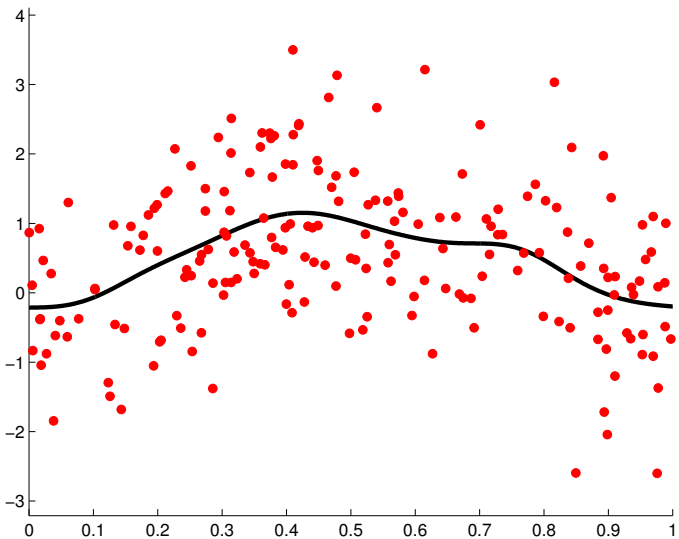
CAPUSHE (Baudry, Maugis & Michel, 2011): slope



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Nadaraya-Watson estimator ($\sigma = 0.01$)



Linear estimators

- OLS: $\hat{F}_m = \Pi_{S_m} Y$ (projection onto S_m)
- (kernel) ridge regression, spline smoothing (Wahba, 1990):

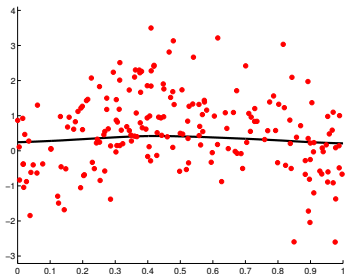
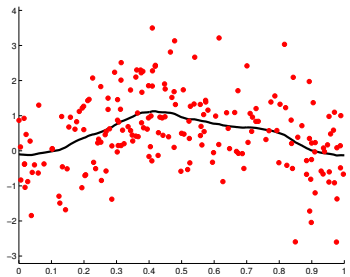
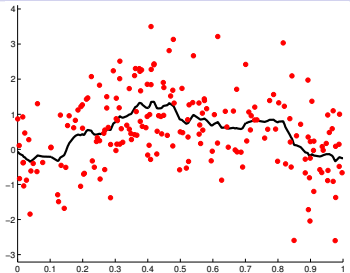
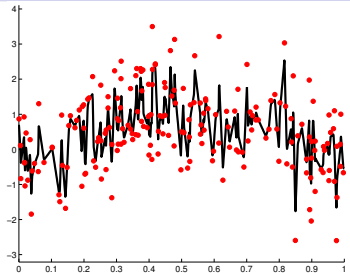
$$\hat{F}_i = \hat{f}(x_i) \quad \text{with} \quad \hat{f} \in \operatorname{argmin}_{f \in \mathcal{F}_K} \left\{ \frac{1}{n} \sum_{i=1}^n (Y_i - f(x_i))^2 + \lambda \|f\|_{\mathcal{F}_K}^2 \right\}$$

$$\Rightarrow \hat{F}_{\lambda, K} = K(K + \lambda I)^{-1} Y \quad \text{where} \quad K = (K(x_i, x_j))_{1 \leq i, j \leq n}$$

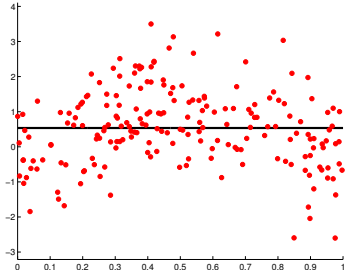
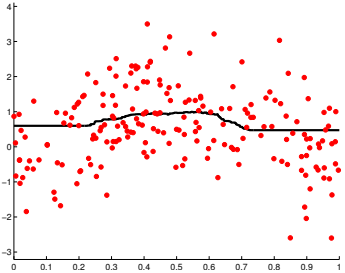
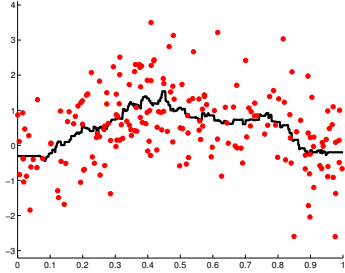
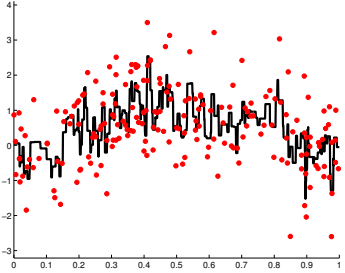
- k -nearest neighbours
- Nadaraya-Watson estimators

$$\hat{F} = AY \quad \text{where } A \text{ does not depend on } Y$$

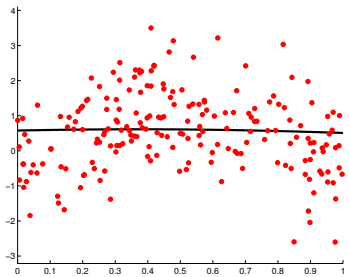
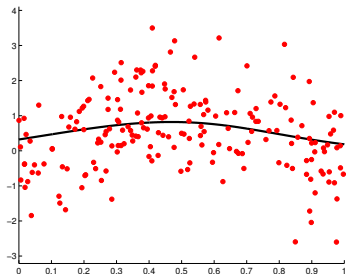
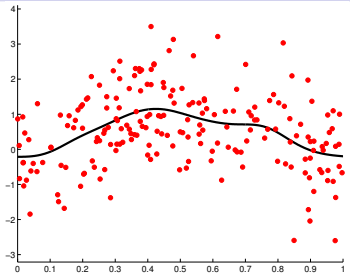
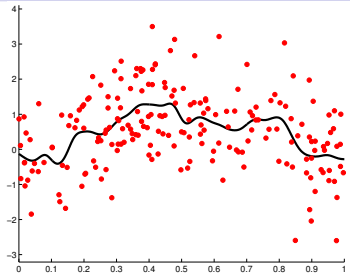
Estimator selection: kernel ridge



Estimator selection: k nearest neighbours



Estimator selection: Nadaraya-Watson



Slope heuristics for linear estimators?

OLS

$$\text{pen}_{\text{Cp}}(m) = \frac{2\sigma^2 D_m}{n}$$

$$\operatorname{argmin}_{m \in \mathcal{M}} \left\{ \frac{1}{n} \|\widehat{F}_m - Y\|^2 + c \frac{D_m}{n} \right\}$$

$\Rightarrow D_{\widehat{m}(c)}$ “jumps” at $\widehat{C}_{\text{jump}} \approx \sigma^2$

\Rightarrow optimal choice with $\widehat{m}(2\widehat{C}_{\text{jump}})$

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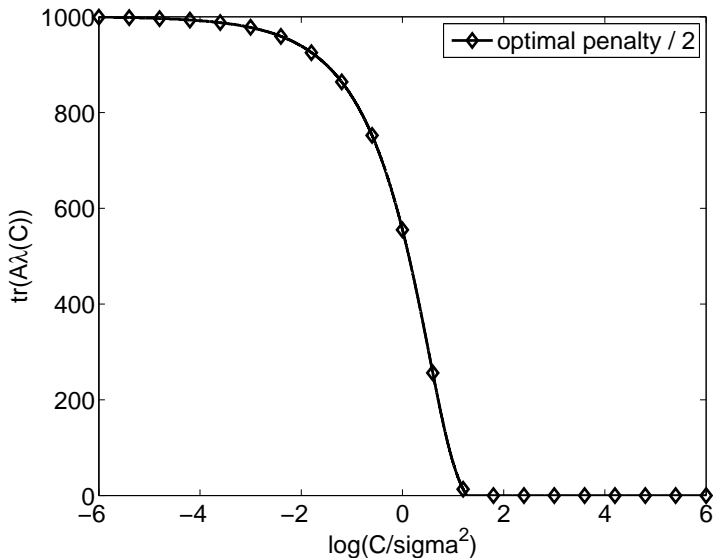
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Does $\operatorname{tr}(A_{\widehat{m}(c)})$ jump at $\widehat{C}_{\text{jump}} \approx \sigma^2$?

optimal choice with $\widehat{m}(2\widehat{C}_{\text{jump}})$?

No dimension jump with a penalty $\propto \text{tr}(A_m)$



Minimal penalties for linear estimators

$$\mathbb{E} \left[\frac{1}{n} \left\| \widehat{F}_m - F \right\|^2 \right] = \frac{1}{n} \left\| (I - A_m) F \right\|^2 + \frac{\text{tr}(A_m^\top A_m) \sigma^2}{n} = \text{bias} + \text{variance}$$

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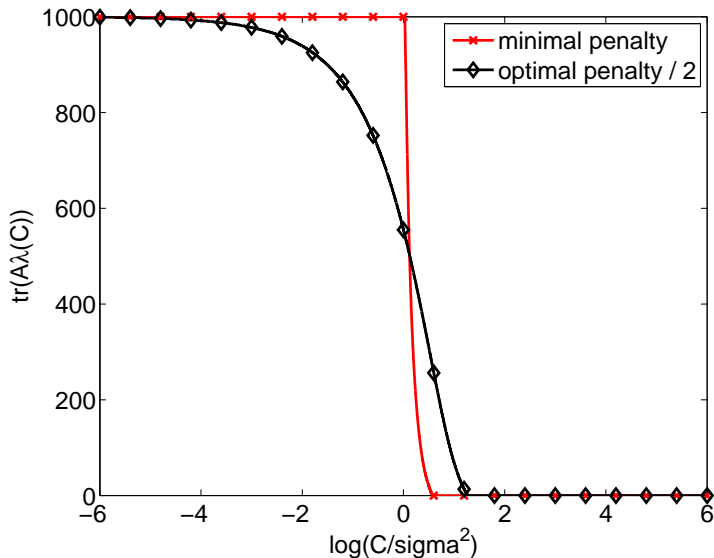
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$$\widehat{m}(C) \in \underset{\lambda \in \Lambda}{\text{argmin}} \left\{ \frac{1}{n} \left\| \widehat{F}_m - Y \right\|^2 + C \times \frac{2 \text{tr}(A_m) - \text{tr}(A_m^\top A_m)}{n} \right\}$$

“Dimension” jump (ridge regression)



Penalty calibration algorithm (A. & Bach 2009)

- 1 for every $C > 0$, compute

$$\hat{m}_{\min}(C) \in \operatorname{argmin}_{m \in \mathcal{M}} \left\{ \frac{1}{n} \left\| Y - \hat{F}_m \right\|^2 + \frac{C (2 \operatorname{tr}(A_m) - \operatorname{tr}(A_m^\top A_m))}{n} \right\}$$

- 2 find \hat{C}_{jump} such that $\operatorname{tr}(A_{\hat{m}_{\min}(C)})$ is “too large” when $C < \hat{C}_{\text{jump}}$ and “reasonably small” when $C > \hat{C}_{\text{jump}}$,

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Theorem for linear estimators

Theorem (A. & Bach 2009–2011)

Assumptions:

- $\forall m \in \mathcal{M}, \|A_m\| \leq L_1$ and $\text{tr}(A_m^\top A_m) \leq \text{tr}(A_m) \leq n$
- $\exists m_0, m_1 \in \mathcal{M}, A_{m_1} = I_n, D_{m_0} \leq \sqrt{n}$ and $\frac{1}{n} \|F_{m_0} - F\|^2 \leq \sigma^2 \sqrt{\log(n)/n}$.
- *Gaussian noise:* $\varepsilon_i \sim \mathcal{N}(0, \sigma^2)$

Then, $\forall \gamma > 0, n \geq n_0(\gamma)$, w.p. at least $1 - 6 \text{Card}(\mathcal{M})n^{-\gamma}$,

$$\forall C < (1 - \eta_n^-) \sigma^2, \quad D_{\hat{m}(C)} \geq \frac{n}{3}$$

$$\forall C > (1 + \eta_n^+) \sigma^2, \quad D_{\hat{m}(C)} \leq \frac{n}{10}$$

with $\eta_n^- = \eta_n^+ = L_2 \delta \sqrt{\frac{\log(n)}{n}}$.

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 $\forall C \in (1 - \eta_n^-, 1 + \eta_n^+)$, $\eta \in (0, 2)$,

$$\forall \hat{m} \in \underset{m \in \mathcal{M}}{\text{argmin}} \left\{ \frac{1}{n} \|Y - \hat{F}_m\|^2 + \frac{2C \text{tr}(A_m)}{n} \right\},$$

$$\frac{1}{n} \|\hat{F}_{\hat{m}} - F\|^2 \leq (1 + \eta) \inf_{m \in \mathcal{M}} \left\{ \frac{1}{n} \|\hat{F}_m - F\|^2 \right\} + \frac{L_3 \gamma^2 \log(n) \sigma^2}{\eta n}$$

Comparison with least-squares

- Linear estimators:

$$\text{pen}_{\min}(m) = \frac{\sigma^2 (2 \text{tr}(A_m) - \text{tr}(A_m^\top A_m))}{n}$$

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- Least-squares case:

$$A_m^\top A_m = A_m \quad \Rightarrow \quad \frac{\text{pen}_{\text{opt}}(m)}{\text{pen}_{\min}(m)} = 2 \quad \Rightarrow \quad \text{Slope heuristics}$$

The k -nearest neighbours case

$$\forall i, j \in \{1, \dots, n\}, \quad A_{i,j} \in \left\{ 0, \frac{1}{k} \right\}$$

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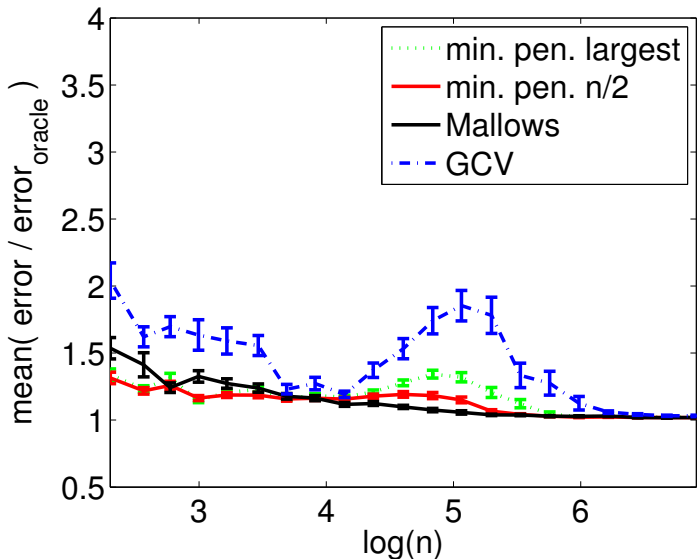
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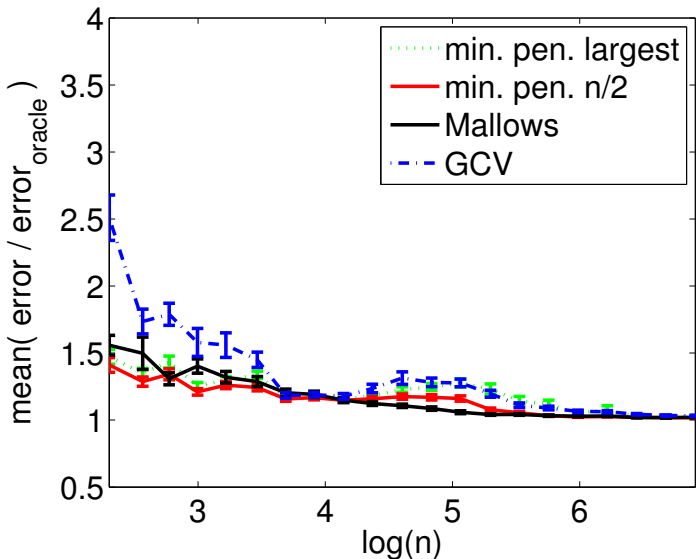
$$\Rightarrow \quad \text{tr}(A) = \frac{n}{k} = \text{tr}(A^T A)$$

$$\Rightarrow \quad \text{pen}_{\text{opt}} = 2 \text{pen}_{\text{min}}$$

Simulations: N-W, $F_i = \sin(25\pi x_i^3)$, $n = 200$



Simulations: ridge, $F_i = \sin(25\pi x_i^3)$, $n = 200$



General framework

- Goal: find from data $t \in \mathbb{S}$ with $\mathcal{R}(t)$ minimal.
- Empirical risk $\widehat{\mathcal{R}}_n(t)$
- Collection of estimators $(\widehat{s}_m)_{m \in \mathcal{M}}$
- Oracle inequality:

$$\mathcal{R}(\widehat{s}_{\widehat{m}}) - \mathcal{R}(s^*) \leq K_n \inf_{m \in \mathcal{M}} \{\mathcal{R}(\widehat{s}_m) - \mathcal{R}(s^*)\} + R_n$$

where $\mathcal{R}(s^*) := \inf_{t \in \mathbb{S}} \mathcal{R}(t)$.

General algorithm

Input: $\forall m \in \mathcal{M}$, $\widehat{\mathcal{R}}_n(\widehat{s}_m)$, $\text{pen}_0(m)$, $\text{pen}_1(m)$ and \mathcal{C}_m

- 1 for every $C > 0$, compute

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Example (slope heuristics): $\text{pen}_1 = 2 \text{pen}_0$

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Key tools: concentration inequalities for $\delta(m) - \delta(m')$, $p_2(m)$ (Wilks phenomenon: Boucheron & Massart, 2010; Spokoiny, 2012; Andresen & Spokoiny, 2013) and $p_1(m)$ (Saumard, 2010–2012)

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- **Specification probabilities in general random fields**, least-squares/Kullback risks, empirical contrast minimizers (Lerasle & Takahashi, 2011)

Theoretical results (2)

- Linear estimators, regression (A. & Bach, 2009–2011)
- Fixed-design regression, **complete variable selection (many models)**, homoscedastic Gaussian noise (Birgé & Massart, 2007)
- **Context tree estimation**, Kullback risk, maximum-likelihood estimators, mixing data (Garivier & Lerasle, 2011)
- Partial proofs in other settings (Baraud, Giraud & Huet, 2009; Verzelen, 2010; Giraud, 2011)

Resampling and minimal penalties

Problem: some of the theoretical results work for

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⇒ **Resampling-based estimator:**

$$C_W \mathbb{E} \left[\widehat{\mathcal{R}}_n^W(\widehat{s}_m) - \widehat{\mathcal{R}}_n^W(\widehat{s}_m^W) \mid \xi_1, \dots, \xi_n \right]$$

Heteroscedastic regression (A., 2008–09), density estimation (Lerasle, 2009)

C_W often unknown (or known only asymptotically) ⇒ estimate it with the minimal penalty algorithm

Generalization: phase transition and parameter tuning

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- Partial theoretical results in least-squares density estimation: **hard thresholding** estimators (Reynaud-Bouret & Rivoirard, 2010; Reynaud-Bouret, Rivoirard & Tuleau-Malot, 2011), **Dantzig** estimator (Bertin, Le Pennec & Rivoirard, 2011)

Empirical results

- Large collection of models: Change-point detection (Lebarbier, 2005)
- Gaussian mixture models (Maugis & Michel, 2008–2010)
- Binary (supervised) classification (Zwald & Blanchard, 2005)
- Unsupervised classification (Baudry, 2009)
- Computational geometry (Caillerie & Michel, 2009)
- Lasso (Connault, 2011)
- ...

(see Baudry, Maugis & Michel, 2011)

Outline

- 1 Motivation
- 2 Slope heuristics for ordinary least-squares
 - Framework
 - Optimal model selection
 - Minimal penalty and the slope heuristics
 - Theoretical results
 - Variance estimation
 - Practical considerations
- 3 Generalization: minimal penalties
 - Linear estimators
 - Slope heuristics for linear estimators
 - Minimal penalty algorithm for linear estimators
 - Minimal penalty algorithm in general
- 4 Application to multi-task learning

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⇒ **Estimator** $\hat{s}(Y_1, \dots, Y_n) \in \mathbb{R}^{np}$?

Ridge multi-task regression

$\hat{F} = (\hat{F}_i^j)_{1 \leq i \leq n, 1 \leq j \leq p}$ with $\hat{F}_i^j = \hat{f}^j(x_i)$ and \hat{f} defined by:

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- More generally: for $M \in \mathcal{S}_p^+(\mathbb{R})$,

$$\arg \min_{f \in \mathcal{F}_K^p} \left\{ \frac{1}{np} \sum_{i=1}^n \sum_{j=1}^p \left(Y_i^j - f^j(x_i) \right)^2 + \sum_{j,\ell} M_{j,\ell} \langle f^j, f^\ell \rangle_{\mathcal{F}_K} \right\}$$

Multi-task estimator selection

⇒ Estimators collection $(\hat{F}_M)_{M \in \mathcal{M}}$, $\mathcal{M} \subset \mathcal{S}_p^+(\mathbb{R})$,

with $\hat{F}_M = A_M Y$ and $A_M = (M^{-1} \otimes K) ((M^{-1} \otimes K) + npl_{np})^{-1}$

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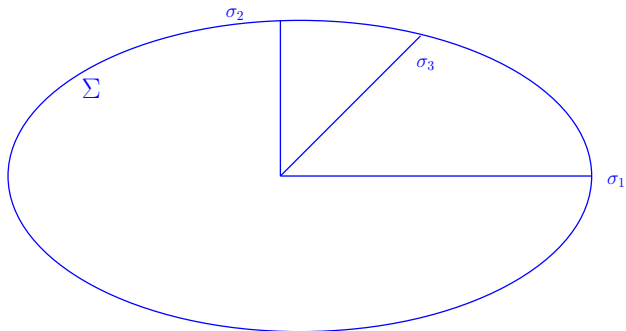
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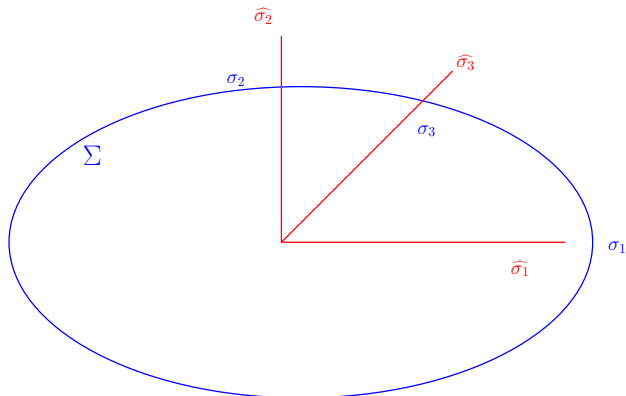
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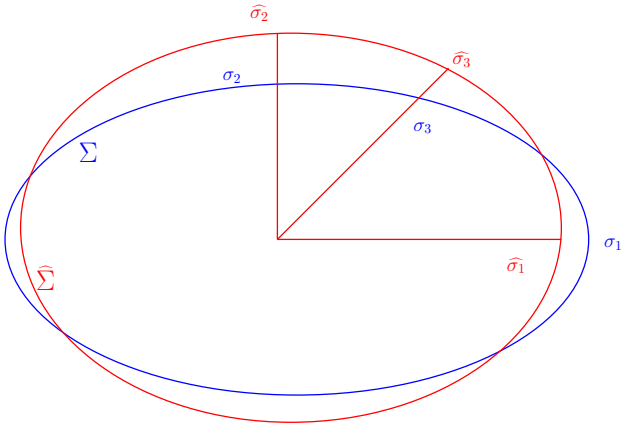
- Problem: How to estimate Σ ?

Estimating the covariance matrix: idea ($p = 2$)



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- for every $j \in \{1, \dots, p\}$, apply the “minimal penalties” algorithm to the data set $(Y_i^j)_{1 \leq i \leq n}$
 \Rightarrow estimator $a(e_j)$ of $\Sigma_{j,j}$
- for every $j \neq \ell \in \{1, \dots, p\}$, apply the “minimal penalties” algorithm to the data set $(Y_i^j + Y_i^\ell)_{1 \leq i \leq n}$
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- Recover an estimator $\hat{\Sigma}$ of Σ :

$$\hat{\Sigma} = J(a(e_1), \dots, a(e_p), a(e_1 + e_2), \dots, a(e_{p-1} + e_p))$$

where J is the unique linear application $R^{p(p+1)/2} \mapsto \mathcal{S}_p(\mathbb{R})$ such that

$$\Sigma = J(\Sigma_{1,1}, \dots, \Sigma_{p,p}, \Sigma_{1,1} + \Sigma_{2,2} + 2\Sigma_{1,2}, \dots, \Sigma_{p-1,p-1} + \Sigma_{p,p} + 2\Sigma_{p-1,p})$$

Theorem: Estimating the covariance matrix

Theorem (Solnon, A. & Bach, 2011)

If for every $j = 1, \dots, p$, some $\lambda_j > 0$ exists such that $\text{tr}(A_{\lambda_j}) \leq \sqrt{n}$ and

$$\frac{1}{n} \|(I_n - A_{\lambda_j})F^j\|^2 \leq \Sigma_{j,j} \sqrt{\frac{\ln(n)}{n}} \quad \text{where} \quad A_{\lambda_j} = K(K + n\lambda_j I_n)^{-1},$$

Then, with probability $1 - L_5 p^2 n^{-\delta}$, if $n \geq n_0(\delta)$,

$$(1 - \eta)\Sigma \preceq \hat{\Sigma} \preceq (1 + \eta)\Sigma \quad \text{with} \quad \eta := L(2 + \delta)c(\Sigma)^2 p \sqrt{\frac{\ln(n)}{n}}$$

where $c(\Sigma) = \max(\text{Sp}(\Sigma)) / \min(\text{Sp}(\Sigma))$.

⇒ sufficient condition for consistency

Theorem: Oracle inequality

Theorem (Solnon, A. & Bach, 2011)

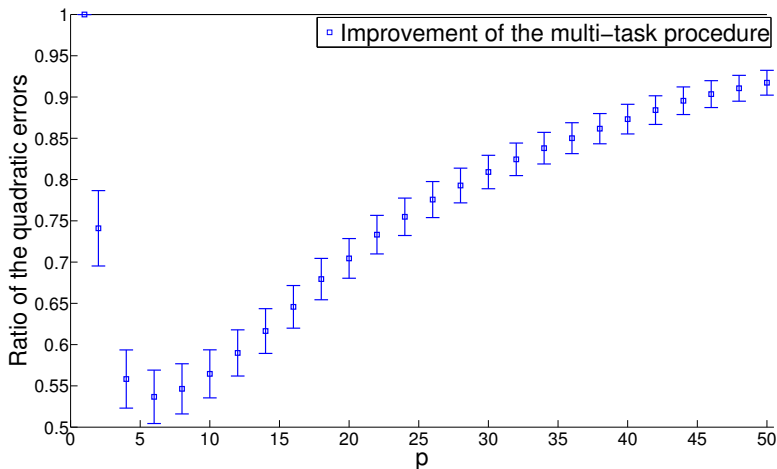
If moreover matrices $M \in \mathcal{M}$ can be diagonalized in the same orthogonal basis, and if

$$\hat{M} \in \arg \min_{M \in \mathcal{M}} \left\{ \frac{1}{np} \left\| \hat{F}_M - Y \right\|^2 + \frac{2}{np} \operatorname{tr} \left(A_M \left(\hat{\Sigma} \otimes I_n \right) \right) \right\},$$

Then, with probability $1 - L_5 p^2 n^{-\delta}$, if $n \geq n_0(\delta)$,

$$\begin{aligned} \frac{1}{np} \left\| \hat{F}_{\hat{M}} - F \right\|^2 &\leq \left(1 + \frac{1}{\ln(n)} \right)^2 \inf_{M \in \mathcal{M}} \left\{ \frac{1}{np} \left\| \hat{F}_M - F \right\|^2 \right\} \\ &\quad + L(2 + \delta)^2 c(\Sigma)^4 \frac{\operatorname{tr}(\Sigma)}{p} \frac{p^3 \ln(n)^3}{n} \end{aligned}$$

Simulations: $n = 100$, $2 \leq p \leq 50$, $1.1 \leq c(\Sigma) \leq 22.5$



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- ⇒ **Extend/adapt results** to other estimators/learning algorithms (e.g., SVM or Lasso-type)? Other losses?
Key question: **compute/estimate the expectation** and prove **concentration inequalities** for

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- ⇒ What if \mathcal{M} is **“large”** (e.g., variable selection with $p \geq n$ explanatory variables)?