

#### Abstract

We are interested in the asymptotic *distance to nearest neighbour* (or *gap*) statistic of Gaussian fractions  $\frac{p}{a}$ , with  $p, q \in \mathbb{Z}[i]$  and  $0 < |q| \leq N$ , as  $N \to \infty$ . We use the homogeneous dynamical approach of J. Marklof [Mar13] in order to derive the existence of a probability measure describing this asymptotic gap statistic.

## Introduction

The Gaussian fractions with height at most N > 0 are defined as the points of the square torus in

$$\mathcal{G}_N = \left\{ egin{smallmatrix} p & ext{mod} \mathbb{Z}[i] : p, q \in \mathbb{Z}[i], 0 < |q| \leq N 
ight\} \subset \mathbb{C}/\mathbb{Z}[i].$$

**Figure 1:** The set  $\mathcal{G}_{20}$  with colours of points depending on their height. The cardinality of  $\mathcal{G}_N$  can be estimated by Mertens' formula, as  $N \rightarrow \infty$ ,

card  $\mathcal{G}_N \sim c N^4$  where  $c = \frac{\pi}{2 \zeta_{\mathbb{Q}(i)}(2)}$ .

Let dx be the Haar probability measure on the square torus  $\mathbb{C}/\mathbb{Z}[i]$  and let  $\Delta_r$  denote the Dirac mass at any point r. Then the Gaussian fractions equidistribute.

**Theorem** (S. Cosentino, 1999). We have the vague convergence, as  $N \to \infty$ ,

$$\frac{1}{\operatorname{card} \mathcal{G}_N} \sum_{r \in \mathcal{G}_N} \Delta_r \stackrel{*}{\rightharpoonup} dx.$$

This means that, as  $N \to \infty$ , the set  $\mathcal{G}_N$  becomes denser and denser in a uniform way in  $\mathbb{C}/\mathbb{Z}[i]$ .

Nevertheless, the Gaussian fractions do not look as uniformly distributed in the square torus as the evenly spaced Riemann fractions  $\mathcal{R}_N = \{ \frac{p}{N} \mod \mathbb{Z}[i] : p \in \mathbb{Z}[i] \}$ . An explanation lays in the asymptotic study of gaps in the sequence  $(\mathcal{G}_N)_{N \in \mathbb{N}^*}$ .

Let us define the probability measures

$$\mu_N = \frac{1}{\operatorname{card} \mathcal{G}_N} \sum_{r \in \mathcal{G}_N} \Delta_{N^2 d(r, \mathcal{G}_N \smallsetminus \{r\})}$$

That is,  $\mu_N$  is the uniform probability measure on the multiset of scaled gaps

$$\{\{N^2 d(r, \mathcal{G}_N \smallsetminus \{r\}) : r \in \mathcal{G}_N\}\}.$$

The scaling factor  $N^2$  here has been chosen with comparison to the average area  $a_N$  of any partition of  $\mathcal{G}_N$  (e.g. its Voronoï cells) since  $\sqrt{a_N} = \frac{1}{\sqrt{\operatorname{card} \mathcal{G}_N}} \sim \frac{1}{\sqrt{c N^2}}$ .

**Theorem** (R. Sayous, 2024). *There exists a probability mea*sure  $\mu$  on  $\mathbb{R}$  such that, as  $N \to \infty$ ,

 $\mu_N \rightharpoonup \mu$ .

Moreover,  $\mu$  has support  $[1, +\infty)$  and has a density with respect to the Lebesgue measure.



**Figure 2:** A numerical approximation of the density of  $\mu$ , using points of  $\mathcal{G}_{50}$ .

In comparison, all scaled gaps in the Riemann fractions  $\mathcal{R}_N$  are equal to  $N d(\frac{p}{N}, \mathcal{R}_N \setminus \{\frac{p}{N}\}) = 1.$ 

## An integral formula and a tail estimate

For  $z \in \mathbb{C}$  and  $r, R \ge 0$ , let  $A(z_0, r, R) = \{z \in \mathbb{C} : r \le |z - z_0| \le R\}$ denotes the closed annulus in  $\mathbb{C}$  centred at z with radii r and R. We have the following integral formula for the cumulative distribution function of  $\mu$ .

**Theorem (R. Sayous, 2024).** For every 
$$\delta > 0$$
, we have  

$$\mu([0, \delta]) = 2 \int_{s=0}^{+\infty} dx \Big( \bigcup_{\substack{p,q \in \mathbb{Z}[i] \\ p \neq 0}} A\Big(\frac{q}{p}, \frac{e^s}{\delta}, \frac{e^{\frac{s}{2}}}{|p|}\Big) \mod \mathbb{Z}[i] \Big) e^{-2s} ds$$

From this integral formula and a series of geometric arguments, we can derive the tail estimate, as  $\delta \to +\infty$ ,

$$\mu(]\delta, +\infty[) = \frac{1}{\delta^4} + O\left(\frac{1}{\delta^5}\right).$$



**Figure 3:** At the top, the empirical tail distribution  $\delta \rightarrow \mu_N([\delta, +\infty)]$  (in blue) with N = 30 and the graph of  $\delta \mapsto \frac{1}{54}$  (in red). At the bottom, a logarithmic version of the top graph: we illustrate the tail estimate of  $\mu$  by comparing the functions  $\ell \mapsto \ln(\mu_N(]e^{\ell}, +\infty[))$  and  $\ell \mapsto -4\ell$ .

# Idea of the proof: a link with dynamic on the hyperbolic space $\mathbb{H}^3$

Let us use the upper half-space model of the 3-dimensional (real) hyperbolic space  $\mathbb{H}^3$ . The positive isometries of  $\mathbb{H}^3$  are described by the action of the group  $G = PSL_2(\mathbb{C})$  by homographies on the boundary at infinity  $\partial_{\infty} \mathbb{H}^3 = \mathbb{C} \cup \{\infty\}$ . In particular, (a reparametrisation of) the geodesic flow from  $\infty$  to 0 is given by the Cartan subgroup of G

Translations on each horizontal plane (i.e. on each horosphere centred at  $\infty$ ) are given by the abelian group

And rotations with axis  $]0, \infty[$  give the compact group

Let also  $\Gamma = PSL_2(\mathbb{Z}[i])$  denote the Bianchi group of  $\mathbb{Q}(i)$ . The following theorem is a result of equidistribution of Gaussian fractions set on an horosphere following the geodesic flow towards the boundary at infinity in  $\Gamma \setminus \mathbb{H}^3$ .



 $\mathcal{G}_N$  $\angle$ 



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$$A = \{a(t) : t > 0\} \text{ where } a(t) = \begin{bmatrix} \frac{1}{t} & 0\\ 0 & t \end{bmatrix}$$

$$H = \{h(z) : z \in \mathbb{C}\} \text{ where } h(z) = \begin{bmatrix} 1 & z \\ 0 & 1 \end{bmatrix}$$

$$M = \{m(\theta) : \theta \in \mathbb{R}\} \text{ where } m(\theta) = \begin{bmatrix} e^{-\frac{i\theta}{2}} & 0\\ 0 & e^{\frac{i\theta}{2}} \end{bmatrix}$$

**Theorem** (J. Parkkonen, F. Paulin, 2024). *There exists a* probability measure  $\nu$  on  $M \setminus G / \Gamma$  (explicitly computed in [PP24, Cor. 4.2]) such that we have the vague convergence, as  $N \to \infty$ ,

$$\nu_{N} = \frac{1}{\operatorname{card} \mathcal{G}_{N}} \sum_{r \in \mathcal{G}_{N}} \Delta_{Ma(\frac{1}{N})h(-r)\Gamma} \xrightarrow{*} \nu.$$
$$\mathbb{H}^{3} = \{(z, s) : z \in \mathbb{C}, s > 0\}$$

$$a(N)$$

$$s = \frac{1}{N} \xrightarrow{*} \nu \text{ after taking the quotient by } M \text{ and } \Gamma$$

$$\partial_{\infty} \mathbb{H}^{3} = \mathbb{C} \cup \{\infty\}$$

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> The points  $Ma(\frac{1}{N})h(-r)\Gamma$  with  $r \in \mathcal{G}_N$  may give us information about the gaps in  $\mathcal{G}_N$ . In order to see that, first notice that, modulo the four invertible elements  $\mathbb{Z}[i]^{\times} = \{\pm 1, \pm i\}$ , the data of irreducible fractions  $\frac{p}{a}$  in  $\mathcal{G}_N$  is equivalent to the data of vectors (p,q) in  $\mathbb{Z}[i]^2$  with coprime coordinate p and q. Then, we compute

> > $m(-\theta)$

for every  $\delta > 0$ ,

#### Then it remains:

- an issue here,
- tion of  $\delta$ .

Both steps are detailed in [Say24] and extended to any quadratic number field.

# A look at the Eisenstein fractions

In the case of the Eisenstein fractions, i.e. elements of the quadratic field  $\mathbb{Q}(i\sqrt{3})$ , the study conducted in [Say24] focuses on the asymptotic gap statistics in the following sequence of point clouds in the elliptic curve  $\mathbb{C}/\mathbb{Z}[e^{i\frac{2\pi}{6}}]$ .



**Figure 4:** The Eisenstein fractions of height at most 10 (left) and 20 (right).

## References

[Mar13]	J. Marklo quence" theory"
[PP24]	J. Parkke rays in n
[Say24]	R. Sayou auadrati



$$a\left(\frac{1}{N}\right)h(-z)\begin{pmatrix}p\\q\end{pmatrix} = \begin{pmatrix} \left(\frac{p}{q}-z\right)qNe^{\frac{i\theta}{2}}\\ \frac{q}{N}e^{-\frac{i\theta}{2}} \end{pmatrix}.$$

By taking the modulus of each coordinate, this formula allows to code in a subset  $\mathcal{C}(\delta)$  of  $M \setminus G / \Gamma$  the two conditions that the denominator satisfies  $|q| \leq N$  and that the scaled gap around z is greater than some parameter  $\delta > 0$ . This yields the formula,

$$\mu_N(]\delta, +\infty[) = \nu_N(\mathcal{C}(\delta)).$$

• to prove that the convergence  $\nu_N(\mathcal{C}(\delta)) \rightarrow \nu(\mathcal{C}(\delta))$ , by showing that  $\nu(\partial \mathcal{C}(\delta)) = 0$  and that the noncompactness of  $\mathcal{C}(\delta)$  is not

• to compute  $\nu(\mathcal{C}(\delta))$  and checks that it is a tail distribution func-

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